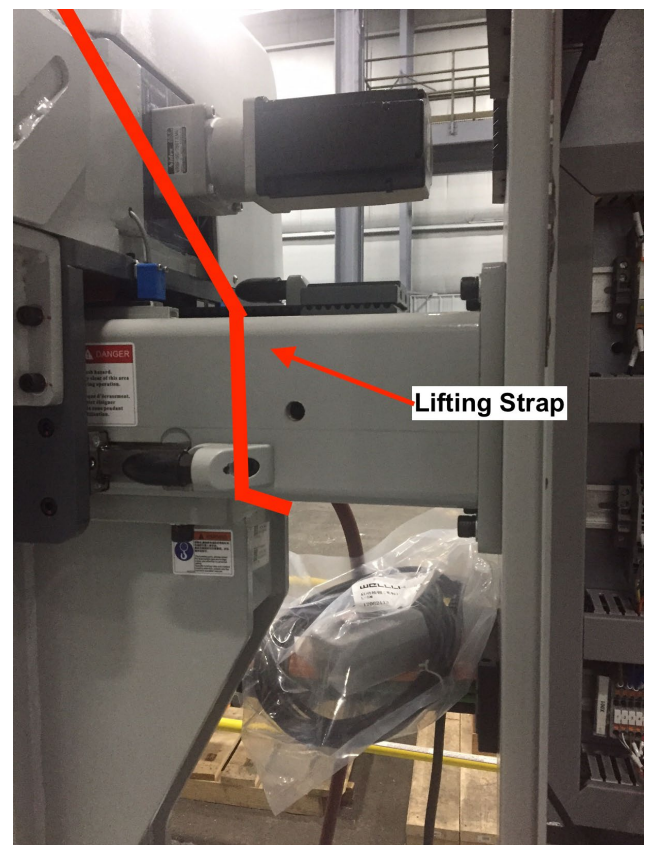
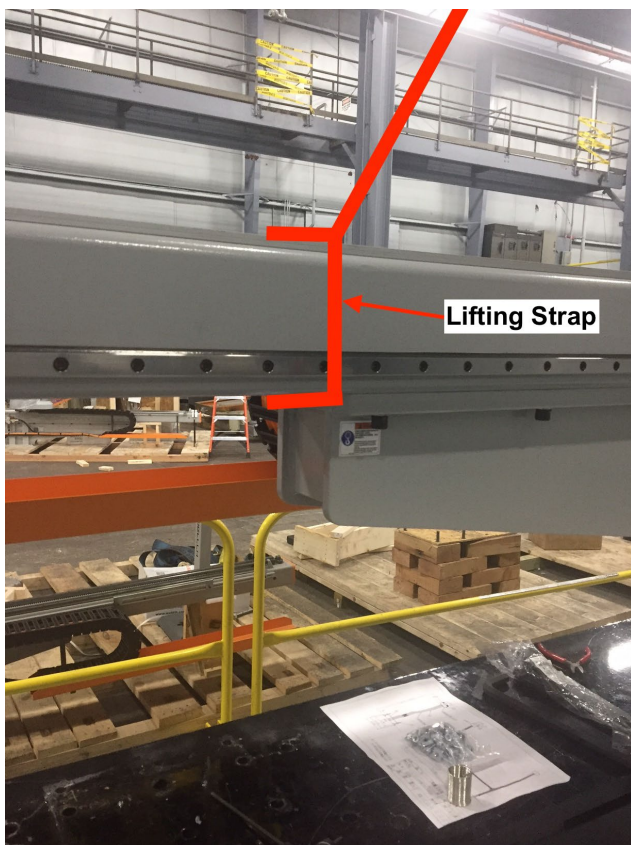


Rigging (C) Series Robots

1. Remove Shipping brackets on traverse beam on either side of Y-Axis sled.
2. Push the X-Axis until it is in the middle of the traverse beam.
3. Locate shipping bracket holes on the middle of traverse beam and attach shipping brackets to these holes, this will balance out the weight distribution to allow for a more level hoist.
4. Once the X-Axis is secure, please attach the appropriate lifting slings/straps to either end of the X-Axis traverse beam. (See below).

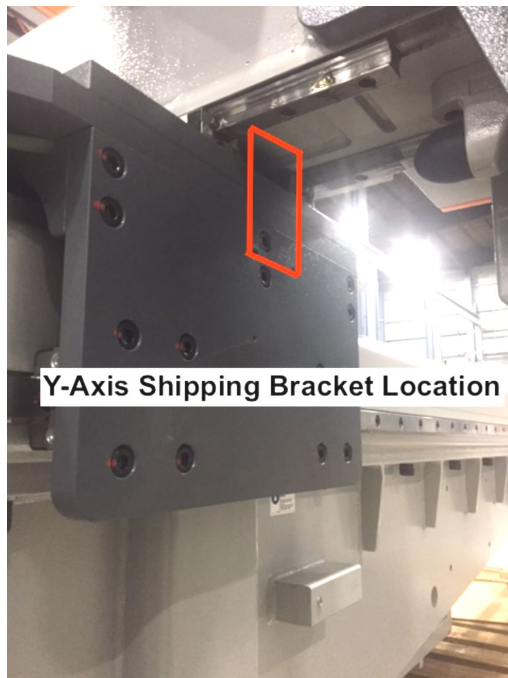


Rigging (C) Series Robots

5. Now Secure a lifting strap around the end of the y-Axis cap.



6. PRIOR TO HOISTING, PLEASE CONFIRM Y-AXIS SHIPPING BRACKET IS SECURE. THIS BRACKET IS LOCATED WHERE THE Z-AXIS MOUNTS TO THE YAXIS. (see below). It is located at the front of the robot.



7. The customer is now ready to hoist the robot. Please ensure that all assembly is completed before mounting the robot to the IMM.